

STAT 714 HW 5 SOLUTIONS

1 For matrices X , A , and B

(a) show that $A X^T X = B X^T X \iff A X^T = B X^T$.

(b) show that $X(X^T X)^-$ is a gen. inverse of X^T .

Solution:

(a) " \Leftarrow " Suppose $A X^T = B X^T$. Then post-multiplication by X gives $A X^T X = B X^T X$.

" \Rightarrow " Suppose $A X^T X = B X^T X$. This implies

$$X^T X A^T = X^T X B^T \Rightarrow X^T X (A^T - B^T) = 0,$$

so the columns of $A^T - B^T$ are in $\text{Nul } X^T X$.

Since $\text{Nul } X^T X = \text{Nul } X$ (we have shown this in class), we have

$$X(A^T - B^T) = 0 \Rightarrow X A^T = X B^T \Rightarrow A X^T = B X^T.$$

(b) Write $X^T X (X^T X)^- X^T X = X^T X$.

This implies $X^T X (X^T X)^- X^T = X^T$ by the result proven in (a).

Therefore $X(X^T X)^-$ is a generalized inverse of X^T .

2 let $Y_i = \mu + \sum_{j=1}^d \beta_j \alpha_{ij} + \epsilon_i$ for $i=1, \dots, n$,

let $(\alpha_{ij})_{1 \leq i \leq n, 1 \leq j \leq d}$ have full-column rank and suppose $\sum_{j=1}^d \alpha_{ij} = 1 \quad \forall i=1, \dots, n$.

(a) Give representation $\underline{y} = X \underline{b} + \underline{e}$

(b) Check if μ is estimable

(c) Give matrix C such that $C \underline{b} = \underline{0}$ imposes $\sum_{j=1}^d \sum_{i=1}^n \alpha_{ij} \beta_j = 0$.

(d) Find $\hat{\mu}$ under the constraint in (c).

Solution:

$$(a) \begin{bmatrix} Y_1 \\ \vdots \\ Y_n \end{bmatrix} = \begin{bmatrix} 1 & \alpha_{11} & \dots & \alpha_{1d} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & \alpha_{n1} & \dots & \alpha_{nd} \end{bmatrix} \begin{bmatrix} \mu \\ \beta_1 \\ \vdots \\ \beta_d \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}.$$

$$\underline{y} = X \underline{b} + \underline{e}$$

(b) $\mu = \underline{c}^T \underline{b}$ with $\underline{c} = (1 \ 0 \dots \ 0)^T$.

To check whether $\underline{c} \in \text{Col } X^T$, build augmented matrix for solving $X^T \underline{x} = \underline{c}$ and row reduce:

$$\begin{bmatrix} 1 & \dots & 1 & \vdots & 1 \\ g_{11} & \dots & g_{n1} & \vdots & 0 \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ g_{1d} & \dots & g_{nd} & \vdots & 0 \end{bmatrix} \sim \begin{bmatrix} 0 & \dots & 0 & \vdots & 1 \\ g_{11} & \dots & g_{n1} & \vdots & 0 \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ g_{1d} & \dots & g_{nd} & \vdots & 0 \end{bmatrix}$$

← Subtract from the first row the sum of all the other rows.

We see that there is no solution, so μ is not estimable.

(c) We may impose the constraint $\sum_{j=1}^d \sum_{i=1}^n g_{ij} \beta_j = 0$ as $C \underline{b} = 0$ with

$$C = \begin{bmatrix} 0 & \sum_{i=1}^n g_{i1} & \dots & \sum_{i=1}^n g_{id} \end{bmatrix}_{1 \times (d+1)}$$

(d) The constrained estimator is the (unique) solution to

$$\begin{bmatrix} X^T X \\ C \end{bmatrix} \underline{b} = \begin{bmatrix} X^T \underline{y} \\ 0 \end{bmatrix}$$

letting $\underline{g}_{\sim j} = (g_{1j}, \dots, g_{nj})^T$ for each $j=1, \dots, d$, we may write

$$X^T X = \begin{bmatrix} n & \underline{1}_n^T \underline{g}_{\sim 1} & \dots & \underline{1}_n^T \underline{g}_{\sim d} \\ \underline{1}_n^T \underline{g}_{\sim 1} & \left(\begin{matrix} \underline{g}_{\sim 1}^T \underline{g}_{\sim 1} \\ \vdots \\ \underline{g}_{\sim i}^T \underline{g}_{\sim j} \\ \vdots \\ \underline{g}_{\sim d}^T \underline{g}_{\sim d} \end{matrix} \right)_{1 \leq i, j \leq d} \\ \underline{1}_n^T \underline{g}_{\sim d} & \dots & \dots & \dots \end{bmatrix} \quad X^T \underline{y} = \begin{bmatrix} n \bar{y} \\ \underline{g}_{\sim 1}^T \underline{y} \\ \vdots \\ \underline{g}_{\sim d}^T \underline{y} \end{bmatrix}$$

From here we row-reduce the augmented matrix:

$$\begin{bmatrix} n & \underline{1}_n^T \underline{g}_{\sim 1} & \dots & \underline{1}_n^T \underline{g}_{\sim d} & \vdots & n \bar{y} \\ \underline{1}_n^T \underline{g}_{\sim 1} & \left(\begin{matrix} \underline{g}_{\sim 1}^T \underline{g}_{\sim 1} \\ \vdots \\ \underline{g}_{\sim i}^T \underline{g}_{\sim j} \\ \vdots \\ \underline{g}_{\sim d}^T \underline{g}_{\sim d} \end{matrix} \right)_{1 \leq i, j \leq d} & \vdots & \vdots & \vdots & \underline{g}_{\sim 1}^T \underline{y} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \underline{1}_n^T \underline{g}_{\sim d} & \dots & \dots & \dots & \vdots & \underline{g}_{\sim d}^T \underline{y} \\ 0 & \underline{1}_n^T \underline{g}_{\sim 1} & \dots & \underline{1}_n^T \underline{g}_{\sim d} & \vdots & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} n & 0 & \dots & 0 & | & n\bar{y} \\ \vdots & \vdots & \vdots & \vdots & | & \vdots \\ 1_{n \times d} & \left(\begin{matrix} g_1^T g_1 \\ \vdots \\ g_d^T g_d \end{matrix} \right)_{1 \leq i, j \leq d} & | & \vdots \\ 0 & 1_{n \times d}^T g_1 & \dots & 1_{n \times d}^T g_d & | & 0 \end{bmatrix} \cdot$$

Subtract last row from first row

This shows that the first entry of the solution \hat{b} to $\begin{bmatrix} X^T X \\ c \end{bmatrix} b = \begin{bmatrix} X^T y \\ 0 \end{bmatrix}$ is \bar{y} .

So $\hat{\mu} = \bar{y}$.

- 13 Let $X_{n \times p}$ have full-column rank with first column a column of ones.
 Let $y_{n \times 1}$ a vector of responses not all equal to the same value.
 Let P_2 be the orth. proj. onto $\text{Span}\{1_n\}$.

(a) Interpret $\frac{\| (P_X - P_2) y \|^2}{\| (I - P_2) y \|^2}$.

(b) Give range of values for quantity in (a)

(c) Write quantity in terms of y_i, \hat{y}_i, \bar{y} .

Solution:

(a) This is the ratio of the "model sum of squares" over the "total sum of squares".

The denominator measures the total variability in y around its mean.

The numerator measures the variability of $P_X y$ around the mean of y .

This is R^2 , the coefficient of determination.

(b) we can write

$$\begin{aligned}\|(\mathbf{I} - \mathbf{P}_1)\tilde{y}\|^2 &= \|(\mathbf{I} - \mathbf{P}_x)\tilde{y} + (\mathbf{P}_x - \mathbf{P}_1)\tilde{y}\|^2 \\ &= \|(\mathbf{I} - \mathbf{P}_x)\tilde{y}\|^2 + \|(\mathbf{P}_x - \mathbf{P}_1)\tilde{y}\|^2 + 2 [(\mathbf{P}_x - \mathbf{P}_1)\tilde{y}] \cdot [(\mathbf{I} - \mathbf{P}_x)\tilde{y}],\end{aligned}$$

where

$$\begin{aligned}[(\mathbf{P}_x - \mathbf{P}_1)\tilde{y}] \cdot [(\mathbf{I} - \mathbf{P}_x)\tilde{y}] &= \tilde{y}^T (\mathbf{P}_x - \mathbf{P}_1) (\mathbf{I} - \mathbf{P}_x) \tilde{y} \\ &= - \tilde{y}^T \mathbf{P}_1 (\mathbf{I} - \mathbf{P}_x) \tilde{y} \\ &= - \tilde{y}^T (\mathbf{P}_1 - \mathbf{P}_1 \mathbf{P}_x) \tilde{y}, \\ &= 0,\end{aligned}$$

since $\mathbf{P}_1 \mathbf{P}_x = \mathbf{P}_1$.

To see why $\mathbf{P}_1 \mathbf{P}_x = \mathbf{P}_1$, note that

$$\mathbf{P}_x \mathbf{P}_1 \tilde{y} = \mathbf{P}_1 \tilde{y} \quad \forall \tilde{y} \text{ since } \mathcal{R}_{\text{non}\{\tilde{1}_n\}} \subset \mathcal{C}(\mathbf{X}).$$

since \mathbf{X} has a column of ones



This gives $\mathbf{P}_x \mathbf{P}_1 = \mathbf{P}_1 \Rightarrow (\mathbf{P}_x \mathbf{P}_1)^T = \mathbf{P}_1^T = \mathbf{P}_1 \Rightarrow \mathbf{P}_1 \mathbf{P}_x = \mathbf{P}_1$.

From the above we have

$$\|(\mathbf{I} - \mathbf{P}_1)\tilde{y}\|^2 = \|(\mathbf{I} - \mathbf{P}_x)\tilde{y}\|^2 + \|(\mathbf{P}_x - \mathbf{P}_1)\tilde{y}\|^2.$$

so the numerator $\|(\mathbf{P}_x - \mathbf{P}_1)\tilde{y}\|^2$ can never exceed the denominator $\|(\mathbf{I} - \mathbf{P}_1)\tilde{y}\|^2$.

The denominator is positive and the numerator is nonnegative, so

$$\frac{\|(\mathbf{P}_x - \mathbf{P}_1)\tilde{y}\|^2}{\|(\mathbf{I} - \mathbf{P}_1)\tilde{y}\|^2} \in [0, 1].$$

4] Let $X = [\tilde{x}_1 \ X_2]$, where X_2 has a column of ones and X has full-column rank.

Let $\hat{b}_1 = (X^T X)^{-1} X^T y$.

(a) Show that $\text{Var } \hat{b}_1 = \frac{\sigma^2}{1-R_1^2} \frac{1}{\|(\mathbb{I}-P_1)\tilde{x}_1\|^2}$, where $R_1^2 = \frac{\|(P_{X_2}-P_1)\tilde{x}_1\|^2}{\|(\mathbb{I}-P_2)\tilde{x}_1\|^2}$.

(b) Interpret.

Solution:

(a) We have
$$\begin{aligned} \text{Cov } \hat{b}_1 &= \text{Cov} \left((X^T X)^{-1} X^T y \right) \\ &= (X^T X)^{-1} X^T [\sigma^2 \mathbb{I}_n] X (X^T X)^{-1} \\ &= \sigma^2 (X^T X)^{-1}. \end{aligned}$$

The variance of \hat{b}_1 is the (1,1) entry of $\sigma^2 (X^T X)^{-1}$.

Using a block matrix inversion formula, we obtain

$$\begin{aligned} \text{Var } \hat{b}_1 &= \sigma^2 \left[\tilde{x}_1^T \tilde{x}_1 - \tilde{x}_1^T X_2 (X_2^T X_2)^{-1} X_2^T \tilde{x}_1 \right]^{-1} \\ &= \frac{\sigma^2}{\tilde{x}_1^T (\mathbb{I} - P_{X_2}) \tilde{x}_1} \\ &= \frac{\sigma^2}{\tilde{x}_1^T ((\mathbb{I} - P_1) - (P_{X_2} - P_1)) \tilde{x}_1} \\ &= \frac{\sigma^2}{\frac{\tilde{x}_1^T (\mathbb{I} - P_1) \tilde{x}_1}{\tilde{x}_1^T (\mathbb{I} - P_1) \tilde{x}_1} - \frac{\tilde{x}_1^T (P_{X_2} - P_1) \tilde{x}_1}{\tilde{x}_1^T (\mathbb{I} - P_1) \tilde{x}_1}} \end{aligned}$$

$$\frac{1}{\tilde{x}_1^T (\mathbb{I} - P_1) \tilde{x}_1}$$

Note: $\tilde{x}_1^T (P_{X_2} - P_1) \tilde{x}_1 = \|(P_{X_2} - P_1)\tilde{x}_1\|^2$
 uses the fact that $P_{X_2} - P_1$ is idempotent.
 This is idempotent because $\text{Span} \{\tilde{x}_1\} \subset \text{Col } X_2$

(b) As R_1^2 approaches 1, $\text{Var } \hat{b}_1$ will "explode". The quantity R_1 expresses how correlated \tilde{x}_1 is with the other columns of X . High correlation/collinearity leads to high variance.

5 Let $\underline{y} = X\underline{b} + \underline{e}$, where $\mathbb{E} \underline{e} = \underline{0}$ and $\text{Cov } \underline{e} = \sigma^2 \mathbf{I}_n$.

Assume eigenvalues of $X^T X$ are all positive.

(a) Show that $X^T X \underline{b} = X^T \underline{y}$ has a unique solution.

(b) Show $\mathbb{E} \|\hat{\underline{b}} - \underline{b}\|^2 = \sigma^2 \sum_{j=1}^p \lambda_j^{-1}$, where $\lambda_1, \dots, \lambda_p$ are the eigenvalues of $X^T X$.

Solution:

(a) Since $X^T X$ has all positive eigenvalues its determinant is nonzero and therefore it is invertible. So

$$\hat{\underline{b}} = (X^T X)^{-1} X^T \underline{y}.$$

(b) We have

$$\begin{aligned} \mathbb{E} \|\hat{\underline{b}} - \underline{b}\|^2 &= \mathbb{E} \left(\hat{\underline{b}}^T \hat{\underline{b}} - 2 \hat{\underline{b}}^T \underline{b} + \underline{b}^T \underline{b} \right) \\ &= \mathbb{E} \hat{\underline{b}}^T \hat{\underline{b}} - \underline{b}^T \underline{b} \quad \downarrow \quad \mathbb{E} \underline{z}^T A \underline{z} = (\mathbb{E} \underline{z})^T A \mathbb{E} \underline{z} + \text{tr}(A(\text{Cov } \underline{z})). \\ &= \underline{b}^T \underline{b} + \text{tr}(\text{Cov } \hat{\underline{b}}) - \underline{b}^T \underline{b} \\ &= \text{tr}(\text{Cov } \hat{\underline{b}}) \quad \downarrow \quad \text{Cov } \hat{\underline{b}} = \sigma^2 (X^T X)^{-1}. \\ &= \sigma^2 \text{tr}((X^T X)^{-1}) \\ &= \sigma^2 \sum_{j=1}^p \frac{1}{\lambda_j}. \end{aligned}$$

Since λ_j^{-1} , $j=1, \dots, p$ are the eigenvalues of $(X^T X)^{-1}$ and the trace of a matrix is the sum of its eigenvalues.

16 Show under $\underline{y} = X\underline{b} + \underline{e}$, $\mathbb{E}\underline{e} = \underline{0}$, a contrast $\underline{c}^T \underline{b}$ is estimable $\Leftrightarrow \underline{c} \in \text{Col } X^T$.

Solution: Firstly, note that $\text{Cov } \underline{e}$ plays no role in determining estimability of a contrast (in class we established this result under $\mathbb{E}\underline{e} = \underline{0}$, so one could have any kind of covariance structure for \underline{e}).

"Estimable" means there exists \underline{a}_0 and \underline{a} such that $\mathbb{E}[\underline{a}_0 + \underline{a}^T \underline{y}] = \underline{c}^T \underline{b} \quad \forall \underline{b}$.

" \Leftarrow " Let $\underline{c} \in \text{Col } X^T$. Then $\exists \underline{a}$ such that $\underline{c} = X^T \underline{a}$.

Then with $\underline{a}_0 = 0$ we have $\mathbb{E}[\underline{a}_0 + \underline{a}^T \underline{y}] = \underline{a}^T X \underline{b} = \underline{c}^T \underline{b} \quad \forall \underline{b}$.

" \Rightarrow " Suppose $\mathbb{E}[\underline{a}_0 + \underline{a}^T \underline{y}] = \underline{c}^T \underline{b}$ for all \underline{b} .

Then $\underline{a}_0 + \underline{a}^T X \underline{b} = \underline{c}^T \underline{b} \quad \forall \underline{b}$,

which implies $\underline{a}_0 = 0$ and $\underline{a}^T X = \underline{c}^T$, so $\underline{c} \in \text{Col } X^T$.

7 Let $X = [x_1 \dots x_p]$ be full-rank with unit columns.

Find the unit vector \tilde{z} and the scalar A such that $\tilde{z}^T x_j = A$ for $j=1, \dots, p$.

Solution:

The condition $\tilde{z}^T x_j = A$ for $j=1, \dots, p$ may be expressed as $X^T \tilde{z} = A \mathbf{1}_p$.

A solution is given by

$$\tilde{z}^* = (X^T)^{-} A \mathbf{1}_p,$$

where $(X^T)^{-}$ is a generalized inverse of X^T .

A generalized inverse of X^T is $X(X^T X)^{-1}$, since $X^T X (X^T X)^{-1} X^T = X^T$.

So we can write $\tilde{z}^* = A X (X^T X)^{-1} \mathbf{1}_p$.

But we must scale the solution so that it has unit norm. This gives

$$\tilde{z} = \frac{1}{\|\tilde{z}^*\|} \tilde{z}^* = \frac{1}{\sqrt{A^2 \mathbf{1}_p^T (X^T X)^{-1} X^T X (X^T X)^{-1} \mathbf{1}_p}} A X (X^T X)^{-1} \mathbf{1}_p = \frac{1}{\|X (X^T X)^{-1} \mathbf{1}_p\|} X (X^T X)^{-1} \mathbf{1}_p.$$

Then

$$X^T \tilde{z} = X^T X (X^T X)^{-1} \mathbf{1}_p \frac{1}{\|X (X^T X)^{-1} \mathbf{1}_p\|} = \frac{1}{\|X (X^T X)^{-1} \mathbf{1}_p\|} \mathbf{1}_p,$$

so $A = \frac{1}{\|X (X^T X)^{-1} \mathbf{1}_p\|}$. We can also write

$$A = \left[\mathbf{1}_p^T (X^T X)^{-1} \mathbf{1}_p \right]^{-\frac{1}{2}}$$

$$\tilde{z} = \left[\mathbf{1}_p^T (X^T X)^{-1} \mathbf{1}_p \right]^{-\frac{1}{2}} X (X^T X)^{-1} \mathbf{1}_p.$$