

NONPARAMETRIC REGRESSION WITH SPLINES

Let

$$Y_i = m(X_i) + \varepsilon_i, \quad i=1, \dots, n,$$

$\varepsilon_1, \dots, \varepsilon_n$ iid with $\mathbb{E} \varepsilon_i = 0$, $\mathbb{E} \varepsilon_i^2 = \sigma^2$, independent of $X_1, \dots, X_n \in [0, 1]$.

Idea: let $b_1, \dots, b_d : [0, 1] \rightarrow \mathbb{R}$ be a set of basis functions and suppose

$$m(x) \approx \sum_{k=1}^d \alpha_k b_k(x).$$

building block
functions that we
can add together
to make more
complicated functions

Then we build the a least-squares estimator

$$\hat{m}_n(x) = \sum_{k=1}^d \hat{\alpha}_k b_k(x),$$

where

$$(\hat{\alpha}_1, \dots, \hat{\alpha}_d) = \underset{\alpha_1, \dots, \alpha_d}{\operatorname{argmin}} \sum_{i=1}^n \left(Y_i - \sum_{k=1}^d \alpha_k b_k(X_i) \right)^2.$$

Exercise: Show that by defining the matrix

$$B = \left(b_k(X_i) \right)_{1 \leq k \leq d, 1 \leq i \leq n}$$

we may write

$$(i) \quad \hat{\alpha} = (\hat{\alpha}_1, \dots, \hat{\alpha}_d)^T = (B^T B)^{-1} B^T Y$$

$$(ii) \quad \hat{m}_n(x) = b_x^T \hat{\alpha}, \quad \text{with } b_x = (b_1(x), \dots, b_d(x))^T.$$

□

Concepts: (i) As $n \rightarrow \infty$, the number of basis functions $d \rightarrow \infty$,
so the approximation

$$m(x) \approx \sum_{k=1}^d \alpha_k b_k(x)$$

improves.

(ii) The quality of this approximation depends on

- the choice of basis functions
- the smoothness of the true function m .

(iii) The approximation is never perfect, so we will always have some approximation bias.

Definition of splines: From Stone (1985):

Let K_n be a positive integer and let

$$I_{nk} = \left[\frac{k-1}{K_n}, \frac{k}{K_n} \right), \quad k = 1, \dots, K_n - 1$$

$$I_{nK_n} = \left[\frac{K_n-1}{K_n}, 1 \right].$$

For $r \geq 1$, define the set of functions

$$M_{n,r} = \left\{ m : [0,1] \rightarrow \mathbb{R} : \begin{array}{l} m \text{ is a polynomial of degree } r \text{ or less} \\ \text{on each interval } I_1, \dots, I_{K_n} \text{ and} \\ m \text{ is } r-1 \text{ times continuously differentiable on } [0,1] \end{array} \right\}$$

The functions in $M_{n,1}$, $M_{n,2}$, and $M_{n,3}$ are called linear, quadratic, and cubic splines, respectively.

Define also

$$M_{n,0} = \left\{ m : [0,1] \rightarrow \mathbb{R} : m \text{ is piecewise constant on } I_1, \dots, I_{K_n} \right\}$$

2

Result of DeBoor (1968):

For each $m \in \mathcal{H}(\beta, L)$ on $[0, 1]$, there exists $m_{n,r}^{\text{spl}} \in \mathcal{M}_{n,r}$ ($r \geq \beta - 1$) such that

$$\|m - m_{n,r}^{\text{spl}}\|_{\infty} \leq C \cdot K_n^{-\beta}$$

Remark: K_n is the # intervals into which we subdivide $[0, 1]$.

Example: For $m \in \mathcal{H}(1, L)$, i.e. $m \in \text{Lipschitz}(L)$, $\exists m_{n,0}^{\text{spl}} \in \mathcal{M}_{n,0}$ s.t.

$$\|m - m_{n,0}^{\text{spl}}\|_{\infty} \leq C \cdot K_n^{-1}$$

↑
piecewise constant

We can see directly that for $m \in \text{Lipschitz}(L)$,

$$\|m - m_{n,0}^{\text{spl}}\|_{\infty} = \max_{1 \leq k \leq K_n} \sup_{x \in I_{nk}} |m(x) - m_{n,0}^{\text{spl}}(x)| \leq L \cdot \frac{1}{K_n}$$

if $m_{n,0}^{\text{spl}}$ a piecewise constant such that, e.g. $m_{n,0}^{\text{spl}}(x) = m\left(\frac{k-1}{K_n}\right)$ for $x \in I_{nk}$, $k=1, \dots, K_n$.

B-spline basis for $\mathcal{M}_{n,r}$:

Let $0 = u_0 < u_1 < \dots < u_K = 1$ be knots.

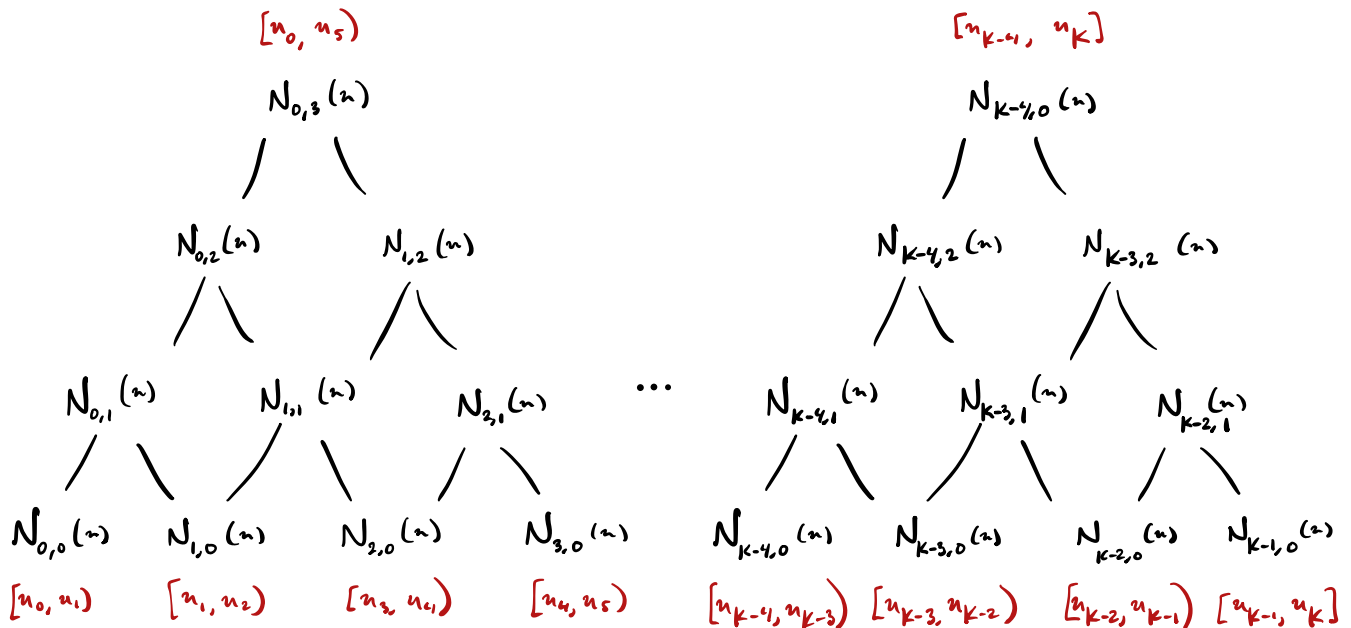
Define the $r=0$ order B-splines based on these knots as

$$N_{k,0}(u) = \begin{cases} 1 & \text{if } u_k \leq u < u_{k+1} \\ 0 & \text{otherwise} \end{cases} \quad \text{for } k=0, 1, \dots, K-1$$

Higher-order B-splines are constructed recursively (Cox-deBoor recursion formula):

$$N_{k,r}(u) = \left(\frac{u - u_k}{u_{k+r} - u_k} \right) N_{k,r-1}(u) + \left(\frac{u_{k+r+1} - u}{u_{k+r+1} - u_{k+1}} \right) N_{k+1,r-1}(u).$$

The recursion has a structure like this:



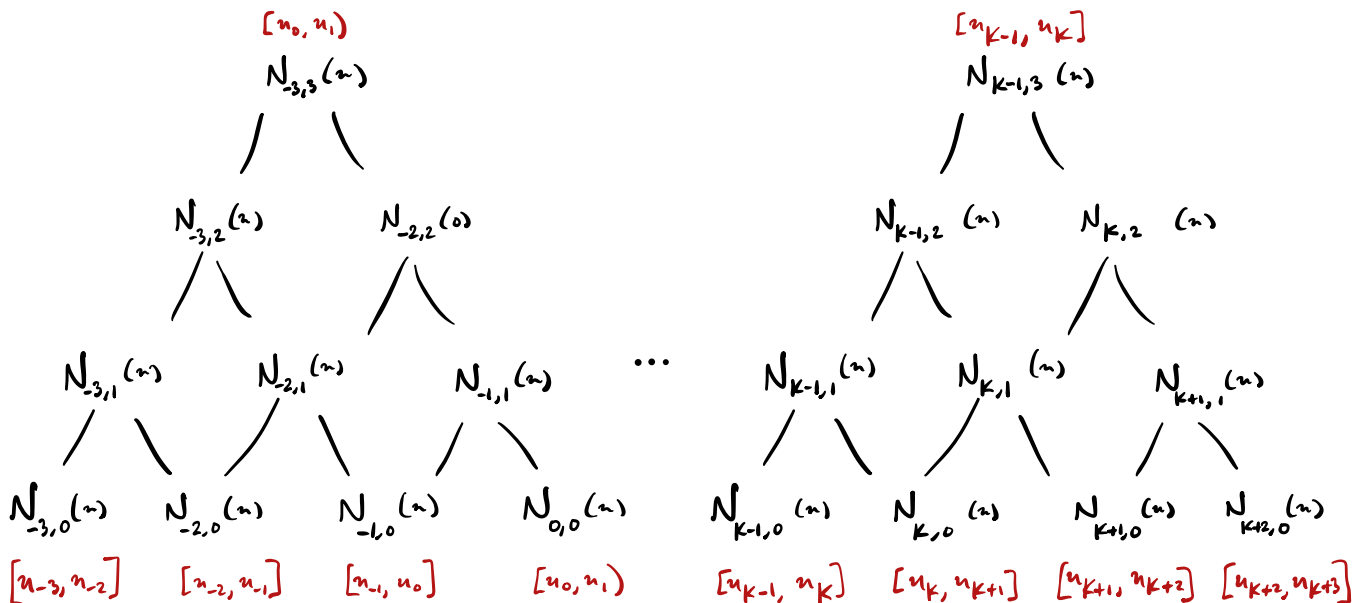
Typically the B-spline basis for splines of order r is constructed by including the end knots $r+1$ times:

For $r=0$, use knots $0 = u_0 < u_1 < \dots < u_K = 1$

For $r=1$, use knots $0 = u_{-1} = u_0 < u_1 < \dots < u_K = u_{K+1} = 1$

For $r \geq 1$ use knots $0 = u_{-r} = \dots = u_0 < u_1 < \dots < u_K = \dots = u_{K+r} = 1$

For $r=3$, the recursion formula under this choice of knots looks like:



Replicating boundary knots in this way, we end up with

$$d_n = K_n + r$$

basis functions when we subdivide $[0,1]$ into K_n intervals and use splines of order r .

Exercise: Make pictures of basis functions using splines from the splines package in R.

Remark: Cubic B-splines ($r=3$) are the most often used in practice.

Equipped with some number d_n of B-spline basis functions, which we now denote by b_1, \dots, b_{d_n} , we have

$$M_{n,r} = \left\{ m: [0,1] \rightarrow \mathbb{R} : m(x) = \sum_{k=1}^{d_n} \alpha_k b_k(x), \alpha_1, \dots, \alpha_{d_n} \in \mathbb{R} \right\}.$$

That is, the functions b_1, \dots, b_{d_n} form a basis for $M_{n,r}$.

We now introduce the least-squares spline estimator

$$\begin{aligned} \hat{m}_{n,r}^{\text{spl}} &= \underset{g \in M_{n,r}}{\operatorname{argmin}} \sum_{i=1}^n \left(y_i - g(x_i) \right)^2, \\ &= \sum_{k=1}^{d_n} \hat{\alpha}_k b_k, \end{aligned}$$

where

$$\begin{pmatrix} \hat{\alpha}_1 \\ \vdots \\ \hat{\alpha}_{d_n} \end{pmatrix}^T = \underset{\alpha \in \mathbb{R}^{d_n}}{\operatorname{argmin}} \left\| \tilde{y} - B \alpha \right\|_2^2, \quad B = \left(b_k(x_i) \right)_{1 \leq k \leq d_n, 1 \leq i \leq n}.$$

Exercise: Generate some data and plot $\hat{m}_{n,r}^{\text{spl}}$ based on splines of order $r=0,1,2,3$.

MSE of $\hat{m}_{n,r}^{\text{spl}}(x_0)$:

Now consider the bias and variance of $\hat{m}_{n,r}^{\text{spl}}(x_0)$ for some $x_0 \in [0,1]$.

Conditions: Let $m \in \mathcal{H}(\beta, L)$ and let $m_{n,r}^{\text{spl}} \in \mathcal{M}_{n,r}$ satisfy $\|m - m_{n,r}^{\text{spl}}\|_{\infty} \leq C \cdot K_n^{-\beta}$.

Let $X_1, \dots, X_n \in [0,1]$ be deterministic such that for some $n_0 > 0$,

$$(C.1) \quad K_n^{-1} c_1 \leq \lambda_{\min}\left(\frac{1}{n} B^T B\right) \leq \lambda_{\max}\left(\frac{1}{n} B^T B\right) \leq C_1 \cdot K_n^{-1}$$

$$(C.2) \quad \left\| \left(\frac{1}{n} B^T B\right)^{-1} \right\|_{\infty} \leq C_2 \cdot K_n$$

$$(C.3) \quad \left\| \frac{1}{n} B^T (m - m_{n,r}^{\text{spl}}) \right\|_{\infty} \leq C_3 \cdot K_n^{-1-\beta},$$

where

$$\tilde{m} = (m(X_1), \dots, m(X_n))^T \quad \text{and} \quad \tilde{m}_{n,r}^{\text{spl}} = (m_{n,r}^{\text{spl}}(X_1), \dots, m_{n,r}^{\text{spl}}(X_n))^T$$

for all $n \geq n_0$, where K_n is the number of subintervals $[0,1]$ is divided into, and C, c_1, C_1, C_2 , and C_3 are positive constants.

We will need the following:

• For a $n \times m$ matrix A , $\|A\|_{\infty} = \max_{1 \leq i \leq n} \sum_{j=1}^m |A_{ij}|$ is the max abs. row sum.

• From the construction of the B-spline basis for $\mathcal{M}_{n,r}$, we have

$$\|b_x\|_2 = 1 \quad \text{as well as} \quad \|b_x\|_2 \leq 1 \quad \text{for all } x \in [0,1].$$

• Moreover, since $m_{n,r}^{\text{spl}}(x_0) = b_{x_0}^T \alpha$ for some $\alpha \in \mathbb{R}^d$, $\tilde{m}_{n,r}^{\text{spl}} = B \alpha$, so that

$$b_{x_0}^T (B^T B)^{-1} B^T \tilde{m}_{n,r}^{\text{spl}} = b_{x_0}^T (B^T B)^{-1} B^T B \alpha = b_{x_0}^T \alpha = m_{n,r}^{\text{spl}}(x_0) \quad \square$$

Result: Bound for $MSE \hat{m}_{n,r}^{spl}(x_0)$

If $m \in \mathcal{H}(\beta, L)$ on $[0, 1]$, then under (C.1), (C.2), and (C.3), for $r \geq \beta - 1$, we have

$$MSE \hat{m}_{n,r}^{spl}(x_0) \leq C \cdot \left(K_n^{-2\beta} + \frac{K_n}{n} \right) \quad \text{for some } C > 0$$

for all $n \geq n_0$.

Exercise: (i) Find the optimal K_n . (ii) Plug in to get optimal MSE.

Solution: Ignoring the constant in front, we have

$$(i) \quad \frac{\partial}{\partial K_n} \left(K_n^{-2\beta} + \frac{K_n}{n} \right) = (-2\beta) K_n^{-2\beta-1} + \frac{1}{n} = 0$$

$$\Leftrightarrow \quad K_n = n^{-\frac{1}{2\beta+1}} \left(\frac{1}{2\beta} \right)^{\frac{1}{2\beta+1}}$$

So choose $K_n = c \cdot n^{-\frac{1}{2\beta+1}}$ for some constant $c > 0$.

(ii) For $K_n = c \cdot n^{-\frac{1}{2\beta+1}}$, we have

$$\begin{aligned} C \cdot \left(K_n^{-2\beta} + \frac{K_n}{n} \right) &= C \cdot \left(c \cdot n^{-\frac{1}{2\beta+1}} \right)^{2\beta} + \frac{c \cdot n^{-\frac{1}{2\beta+1}}}{n} \\ &= C \cdot \left(c^{2\beta} n^{-\frac{2\beta}{2\beta+1}} + c \cdot n^{-\frac{2\beta}{2\beta+1}} \right) \\ &= \tilde{C} \cdot n^{-\frac{2\beta}{2\beta+1}} \end{aligned}$$

for some constant $\tilde{C} > 0$.

□

Proof of bound on MSE $\hat{m}_{n,r}^{spl}(x_0)$:

Variance: We have

$$\text{Var } \hat{m}_{n,r}^{spl}(x_0) = \text{Var} \left[\tilde{b}_{x_0}^T (B^T B)^{-1} B^T Y \right]$$

$$= \tilde{b}_{x_0}^T (B^T B)^{-1} \tilde{b}_{x_0} \sigma^2$$

$$= \frac{1}{n} \tilde{b}_{x_0}^T \left(\frac{1}{n} B^T B \right)^{-1} \tilde{b}_{x_0} \cdot \sigma^2$$

Fact: For A dxd, sym, pos. def.,

$$\sup_{x \in \mathbb{R}^d} \frac{x^T A x}{\|x\|_2^2} = \lambda_{\max}(A)$$

$$\leq \frac{K_n}{n} \underbrace{\|\tilde{b}_{x_0}\|_2^2}_{\leq 1} \lambda_{\max} \left(\left(\frac{1}{n} B^T B \right)^{-1} \right) \cdot \sigma^2$$

$$\leq \frac{K_n}{n} \frac{\sigma^2}{c_1}$$

Bias: We have, for some $\tilde{m}_{n,r}^{spl} \in \mathcal{M}_{n,r}$

$$\mathbb{E} \hat{m}_{n,r}^{spl}(x_0) - m(x_0) = \tilde{b}_{x_0}^T (B^T B)^{-1} B^T \tilde{m} - m(x_0)$$

$\tilde{b}_{x_0}^T (B^T B)^{-1} B^T \tilde{m}_{n,r}^{spl} = \tilde{m}_{n,r}^{spl}(x_0)$,

since $\tilde{m}_{n,r}^{spl} = B \alpha$ for some $\alpha \in \mathbb{R}^d$,

so $\tilde{b}_{x_0}^T (B^T B)^{-1} B^T B \alpha = \tilde{b}_{x_0}^T \alpha = \tilde{m}_{n,r}^{spl}(x_0)$

$$= \tilde{b}_{x_0}^T (B^T B)^{-1} B^T \tilde{m} - \tilde{m}_{n,r}^{spl}(x_0) + \tilde{m}_{n,r}^{spl}(x_0) - m(x_0)$$

$$= \tilde{b}_{x_0}^T (B^T B)^{-1} B^T \left(\tilde{m} - \tilde{m}_{n,r}^{spl} \right) + \tilde{m}_{n,r}^{spl}(x_0) - m(x_0)$$

So the absolute value of the bias is bounded by

$$\left| \mathbb{E} \hat{m}_{n,r}^{spl}(x_0) - m(x_0) \right| \leq \left| \tilde{b}_{x_0}^T (B^T B)^{-1} B^T \left(\tilde{m} - \tilde{m}_{n,r}^{spl} \right) \right| + \left\| \tilde{m}_{n,r}^{spl} - m \right\|_{\infty},$$

when $\left\| \tilde{m}_{n,r}^{spl} - m \right\|_{\infty} \leq C \cdot K_n^{-\beta}$, from de Boer (1968), and

$$\left| \tilde{b}_{x_0}^T (B^T B)^{-1} B^T \left(\tilde{m} - \tilde{m}_{n,r}^{spl} \right) \right| = \left| \tilde{b}_{x_0}^T \left(\frac{1}{n} B^T B \right)^{-1} \left(\frac{1}{n} B^T \left(\tilde{m} - \tilde{m}_{n,r}^{spl} \right) \right) \right| \quad \square$$

$$\begin{aligned}
\|A x\|_1 &= \left\| \begin{pmatrix} a_{11} & \dots & a_{1d} \\ \vdots & & \vdots \\ a_{d1} & \dots & a_{dd} \end{pmatrix} \begin{pmatrix} x_1 \\ \vdots \\ x_d \end{pmatrix} \right\|_1 && \leq \left\| \left(\frac{1}{n} B^T B \right)^{-1} b_{x_0} \right\|_1 \left\| \frac{1}{n} B^T (m - \tilde{m}_{n,r}^{\text{sol}}) \right\|_\infty \\
&= \left\| x_1 \begin{pmatrix} a_{11} \\ \vdots \\ a_{d1} \end{pmatrix} + \dots + x_d \begin{pmatrix} a_{1d} \\ \vdots \\ a_{dd} \end{pmatrix} \right\|_1 && \leq \underbrace{\|b_{x_0}\|_1}_{\leq 1} \left\| \left(\frac{1}{n} B^T B \right)^{-1} \right\|_\infty \left\| \frac{1}{n} B^T (m - \tilde{m}_{n,r}^{\text{sol}}) \right\|_\infty \\
&\leq \|x\|_1 \max_{1 \leq k \leq d} \left\| \begin{pmatrix} a_{1k} \\ \vdots \\ a_{dk} \end{pmatrix} \right\|_1 && \leq C_2 \cdot K_n \cdot C_3 \cdot K_n^{-1-\beta}.
\end{aligned}$$

Putting the bias and variance bounds together completes the proof. \square

Exercise: Let $m \in \text{Lipschitz}(L)$, with $\tilde{m}_{n,0}^{\text{sol}} \in \mathcal{M}_{n,0}$, i.e. piecewise constant.

(i) Give $\lambda_{\min} \left(\frac{1}{n} B^T B \right)$ and $\lambda_{\max} \left(\frac{1}{n} B^T B \right)$

(ii) Give $\left\| \left(\frac{1}{n} B^T B \right)^{-1} \right\|_\infty$.

(iii) Give $\left\| \frac{1}{n} B^T (m - \tilde{m}_{n,0}^{\text{sol}}) \right\|_\infty$.

(iv) Discuss reasonable bounds for these quantities

Then discuss assumptions about x_1, \dots, x_n needed to bound these. Talk about $\text{MSE}_{\tilde{m}_n^{\text{sol}}}(x_0)$ in this setting.

Solution: First: $B = \left(\mathbb{1}(x_i \in I_{nk}) \right)_{1 \leq k \leq K_n, 1 \leq i \leq n}$, so

$$\left(\frac{1}{n} B^T B \right) = \text{diag} \left(\frac{\#\{x_i \in I_{n1}\}}{n}, \dots, \frac{\#\{x_i \in I_{nK_n}\}}{n} \right).$$

This gives

$$\begin{aligned}
\lambda_{\min} \left(\frac{1}{n} B^T B \right) &= \min_{1 \leq k \leq K_n} \frac{\#\{x_i \in I_{nk}\}}{n} \\
\lambda_{\max} \left(\frac{1}{n} B^T B \right) &= \max_{1 \leq k \leq K_n} \frac{\#\{x_i \in I_{nk}\}}{n}.
\end{aligned}$$

\square

Also

$$\left\| \left(\frac{1}{n} B^T B \right)^{-1} \right\|_{\infty} = \max_{1 \leq k \leq K_n} \frac{n}{\#\{X_i \in I_{nk}\}}$$

and

$$\begin{aligned} \left\| \frac{1}{n} B^T (m - \tilde{m}_n^{spl}) \right\|_{\infty} &= \max_{1 \leq k \leq K_n} \left| \frac{1}{n} \sum_{i=1}^n (m(X_i) - m_n^{spl}(X_i)) \mathbb{1}(X_i \in I_{nk}) \right| \\ &\leq \max_{1 \leq k \leq K_n} \left\| m - m_n^{spl} \right\|_{\infty} \frac{\#\{X_i \in I_{nk}\}}{n} \\ &\leq C \cdot K_n^{-1} \cdot \max_{1 \leq k \leq K_n} \frac{\#\{X_i \in I_{nk}\}}{n}. \end{aligned}$$

If we can assume

$$\frac{1}{K_n} \frac{1}{c} \leq \frac{\#\{X_i \in I_{nk}\}}{n} \leq c \frac{1}{K_n} \quad (\star)$$

for some $c > 0$, then we would have

$$(i) \quad \frac{1}{K_n} \frac{1}{c} \leq \lambda_{\min} \left(\frac{1}{n} B^T B \right) \leq \lambda_{\max} \left(\frac{1}{n} B^T B \right) \leq c \frac{1}{K_n}$$

$$(ii) \quad \left\| \left(\frac{1}{n} B^T B \right)^{-1} \right\|_{\infty} \leq c \cdot K_n$$

$$(iii) \quad \left\| \frac{1}{n} B^T (m - \tilde{m}_n^{spl}) \right\|_{\infty} \leq C \cdot K_n^{-1} \cdot c \cdot K_n^{-1}$$

We usually get some version of (\star) by assuming $X_1, \dots, X_n \in [0, 1]$ are generated according to some density f which is bounded away from zero and bounded above.

Our work would lead to

$$\text{MSE } \hat{m}_n^{spl}(x_0) \leq C \cdot \left(K_n^{-2} + \frac{K_n}{n} \right).$$

\square