Integration via Sums

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Integration is a fundamental operation in statistics. Means, variances, and probabilities are integrals; quantiles satify an integral equation; and mixed model likelihoods are obtained via integration.

Only the simplest of integrals can be easily be found in closed form. Programs like *Mathematica* can symbolically integrate many complex functions. Try

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Integrate[x^2*Sin[x]]
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at http://www.wolframalpha.com/.
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However, many intergrals we are interested cannot be found in closed form. We will discuss several numerical approximations to integrals used in statistical computing.

Direct approximations

The simplest approximation to a univariate integral is a *Riemann* sum

$$\int_a^b f(x)dx \approx \Delta \sum_{j=1}^J f(x_j), \ \ \Delta = \frac{b-a}{J}, \ \ x_j = a + \Delta(j-\frac{1}{2}).$$

This version uses the midpoint of the interval.

Instead of assuming $f(\cdot)$ is approximately constant over subintervals, we can instead try to approximate the function over an interval with a simple polynomial; this leads to the trapezoidal rule (linear approximation):

$$\int_{a}^{b} f(x) dx \approx \frac{1}{2} \Delta[f(a) + f(b)] + \Delta \sum_{j=1}^{J-1} f(a+j\Delta),$$

and Simpson's rule (quadratic, p. 137 in G & H, 2013).

Direct methods

- Integrals of the form ∫_{-∞}[∞] f(x)g(x)dx where f(x) is a density can be integrated over the density's effective range for "reasonable" functions g(x), e.g. polynomials. An effective range is a finite interval (a, b) such that ∫_a^b f(x)dx ≈ 1.
- For ∫[∞]_{-∞} f(x)g(x)dx with density f(x), if g(x) has tails that die down as quickly (or more quickly) than f(x), the effective range depends on f(x)g(x), be careful!
- Of course as J increases the approximations become more accurate. There are methods for bounding the apporimxation error for numerical integration.
- Note that the Riemann sum, trapazoidal rule, and Simpson's rule can all be written $\int_a^b f(x) dx \approx \sum_{i=1}^J w_i f(x_i)$.

Example: $E(X^4)$ for $X \sim N(1, 2^2)$.

Quadrature rules also approximate the integral with a sum

$$\int_a^b f(x)dx \approx \sum_{j=1}^J w_j f(x_j).$$

Any quadrature rule picks w_1, \ldots, w_J and x_1, \ldots, x_J to provide an *exact result* for polynomials of at most degree 2J - 1. See

https://en.wikipedia.org/wiki/Gaussian_quadrature.

The nodes x_j are the roots of a polynomial from a class of orthogonal polynomials; see 142–148 in G & H.

R has integrate built-in, which calls the QUADPACK routines QAGS and QAGI for finite and infinite intervals. *Mathematica* has Integrate and NIntegrate.

Quadrature

- Integrals of the form $\int_a^b f(x)dx$ for intervals (a, b) for finite (a, b) are transformed to $\frac{b-a}{2}\int_{-1}^1 f\left(\frac{b-a}{2}x + \frac{a+b}{2}\right)dx$ and typically evaluated using Gauss-Legendre quadrature.
- Integrals of the form $\int_{-1}^{1} \frac{1}{\sqrt{1-x^2}}g(x)dx$ can be evaluated via Chebyshev-Gauss, $\int_{0}^{\infty} e^{-x}g(x)dx$ via Gauss-Laguerre, and $\int_{-\infty}^{\infty} e^{-x^2}g(x)dx$ via Gauss-Hermite.
- If the g(x) is highly localized relative to the weight function, the quadrature breaks down and essentially only uses one point/weight. Adaptive quadrature can help.
- Remember: quadrature is *exact* for polynomials g(x) up to degree 2J - 1. Useful for obtaining moments! Also recall smooth functions can be approximated by polynomials via Taylor's (differentiable) and Weierstrass (continuous) theorems.

Gauss-Hermite quadrature

The most common is integration with respect to a normal density

$$\int_{-\infty}^{\infty} g(x)\phi(x|\mu,\sigma^2)dx.$$

fastGHQuad (univariate) and MultiGHQuad (multivariate) perform
Gauss-Hermite quadrature and multivariate versions.

fastGHQuad computes

$$\int_{-\infty}^{\infty} g(x)e^{-x^2}dx \approx \sum_{j=1}^{J} w_j g(x_j),$$

you pick the number of points/weights J. Note

$$\int_{-\infty}^{\infty} g(y) \frac{1}{\sqrt{2\pi\sigma}} \exp\{-\frac{1}{2\sigma^2} (y-\mu)^2\} = \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\infty} g(\mu + \sqrt{2}\sigma x) e^{-x^2} dx.$$

Example: $E(X^4)$ for $X \sim N(1, 2^2)$. What the smallest J so this is exact?

GLMMs are one place numerical integration is often employed.

Repeated measures Bernoulli data often takes the form $\{(y_{ij}, \mathbf{x}_{ij})\}$ where i = 1, ..., m clusters and $j = 1, ..., n_i$ repeated measurements within a cluster. Positive correlation is induced across the $\mathbf{y}_i = (y_{i1}, ..., y_{in_i})'$ via random effect u_i

$$\operatorname{logit} P(y_{ij} = 1 | u_i) = \mathbf{x}'_i \boldsymbol{\beta} + u_i, \quad u_1, \ldots, u_m \stackrel{iid}{\sim} N(0, \sigma^2).$$

The *i*th likelihood contribution is

$$L_{i} = p(\mathbf{y}_{i}|\boldsymbol{\beta}, \sigma) = \int_{-\infty}^{\infty} \underbrace{\left[\prod_{j=1}^{n_{i}} \frac{\exp\{(\mathbf{x}_{ij}^{\prime}\boldsymbol{\beta}+u)\mathbf{y}_{ij}\}}{1+\exp\{\mathbf{x}_{ij}^{\prime}\boldsymbol{\beta}+u\}}\right]}_{p(\mathbf{y}_{i}|\boldsymbol{\beta},u)} \underbrace{\frac{1}{\sqrt{2\pi\sigma}} \exp\{-\frac{1}{2\sigma^{2}}u^{2}\}}_{p(u|\sigma)} du.$$

Consider the Ache hunting data $\{(m_i, t_i, a_i)\}_{i=1}^{47}$ with hunter-specific random effects:

$$m_i \sim \text{Pois}\{t_i \exp(\beta_0 + \beta_1 a_i + u_i)\}, \ i = 1, \dots, 47.$$

Hunter *i*'s likelihood contribution is, where $\mathbf{x}_i = (1, a_i)'$,

$$L_i = p(m_i|\beta,\sigma) = \int_{-\infty}^{\infty} \exp\{-e^{\mathbf{x}'_i\beta+u}t_i\}e^{m_i(\mathbf{x}'_i\beta+u)}\frac{1}{\sqrt{2\pi\sigma}}\exp\{-\frac{1}{2\sigma^2}u^2\}du.$$

Note that $\frac{t^{m_i}}{m_i!}$ is not needed.

Note that each likelihood contribution L_i consists of two portions as functions of u: one is $N(0, \sigma^2)$ and the other is *approximately* normal when either n_i or t_i are large.

The product of two Gaussians is an unnormalized Gaussian. The multivariate version is

$$\phi_d(\mathbf{x}|\boldsymbol{\mu}_1, \boldsymbol{\Sigma}_1)\phi_d(\mathbf{x}|\boldsymbol{\mu}_2, \boldsymbol{\Sigma}_2) \propto \phi_d(\mathbf{x}|\mathbf{V}[\boldsymbol{\Sigma}_1^{-1}\boldsymbol{\mu}_1 + \boldsymbol{\Sigma}_2^{-1}\boldsymbol{\mu}_2], \mathbf{V}),$$
$$\mathbf{V} = [\boldsymbol{\Sigma}_1^{-1} + \boldsymbol{\Sigma}_2^{-1}]^{-1}.$$

This implies that G-H quadrature around the origin may not be the most efficient/accurate approximation.

Laplace approximations

Want to approximate
$$\int_{\boldsymbol{\theta} \in \mathbb{R}^k} f(\boldsymbol{\theta}) d\boldsymbol{\theta}$$
.

Multivariate Taylor's theorem 2nd-order approximation:

$$g(m{ heta})pprox g(\hat{m{ heta}})+(m{ heta}-\hat{m{ heta}})[
abla g(\hat{m{ heta}})]+rac{1}{2}(m{ heta}-\hat{m{ heta}})'[
abla^2 g(\hat{m{ heta}})](m{ heta}-\hat{m{ heta}}).$$

Take $g(\theta) = \log f(\theta)$ and find $\hat{\theta}$ such that $\nabla g(\hat{\theta}) = \mathbf{0}$. Then

$$\log f(\boldsymbol{\theta}) \approx \log f(\hat{\boldsymbol{\theta}}) - \frac{1}{2}(\boldsymbol{\theta} - \hat{\boldsymbol{\theta}})' [-\nabla^2 \log f(\hat{\boldsymbol{\theta}})](\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}).$$

Exponentiating, recognizing a multivariate normal kernel, and integrating gives

$$\int_{\boldsymbol{\theta} \in \mathbb{R}^k} f(\boldsymbol{\theta}) d\boldsymbol{\theta} \approx f(\hat{\boldsymbol{\theta}}) (2\pi)^{k/2} \left| -\nabla^2 \log f(\hat{\boldsymbol{\theta}}) \right|^{1/2}$$

The more "Gaussian shaped" $f(\cdot)$ is, the better this approximation works.

One can combine the Laplace approximation idea with quadrature to provide highly accurate approximations. Essentially, this method finds $\hat{\theta}$ s.t. $\nabla \log f(\hat{\theta}) = \mathbf{0}$ and uses the approximation

$$f(\boldsymbol{ heta}) \propto \phi_k(\boldsymbol{ heta}|\hat{\boldsymbol{ heta}}, [-
abla^2 \log f(\hat{\boldsymbol{ heta}})]^{-1}),$$

to help "guide" the quadrature points.

SAS proc glimmix documentation has an excellent overview of how this works.

In one dimension, fastGHQuad provides a function to automate adaptive quadrature. Say we want

$$\int_{-\infty}^{\infty}g(x)dx,$$

where $g(\cdot)$ is somewhat Gaussian shaped. Find the mode \hat{x} of g(x), e.g. $\frac{d}{dx} \log g(\hat{x}) = 0$ (perhaps via Newton-Raphson) as well as the scale $\sqrt{1/[-\frac{d^2}{dx^2}\log g(\hat{x})]}$. Then aghQuad(g,mode,scale,rule) approximates the integral.

rule=gaussHermiteData(1) gives a Laplace approximation, otherwise rule=gaussHermiteData(J) for J > 1 uses Gauss-Hermite quadrature.

Ache Poisson regression

We'll show for

$$p(m_i|\beta,\sigma) = \int_{-\infty}^{\infty} \underbrace{\exp\{-e^{\mathbf{x}_i'\beta+u}t_i\}e^{m_i(\mathbf{x}_i'\beta+u)}\frac{1}{\sqrt{2\pi\sigma}}\exp\{-\frac{1}{2\sigma^2}u^2\}}_{g(u)}du,$$

that

$$\frac{d}{dx}\log g(u) = -t_i e^{\mathbf{x}_i'\beta + u} + m_i - \frac{u}{\sigma^2},$$

and

$$\frac{d^2}{dx^2}\log g(u) = -t_i e^{\mathbf{x}'_i \beta + u} - \frac{1}{\sigma^2}.$$

Thus, for a given β , we can perform Newton-Raphson as to find \hat{u}_i via

$$u_{j} = u_{j-1} - \frac{-t_{i}e^{\mathbf{x}_{i}'\beta + u_{j-1}} + m_{i} - \frac{u_{j-1}}{\sigma^{2}}}{-t_{i}e^{\mathbf{x}_{i}'\beta + u_{j-1}} - \frac{1}{\sigma^{2}}}.$$

Example: Ache hunting data using adaptive G-H quadrature.

Quadrature & Laplace approximations

- Laplace approximation used in SAS proc glimmix with method=laplace; also used in the glmer function in the lme4 package as default.
- proc glimmix also implements adaptive quadrature via method=quad(qpoints=6) using the "guiding" idea on the previous slide. If you omit the qpoints option glimmix also adaptively chooses the *number* of points/weights. qpoints=1 is equivalent to laplace, but the latter allows fitting more general models in SAS.
- glmer also can perform adaptive quadrature via, e.g. nAGQ=100.
- Quadrature is also used in SAS proc nlmixed to fit general models with random effects.

- Quadrature and/or Laplace approximations can be used in lower-dimensional problems but break down in moderate to high-dimensional problems, e.g. k ≥ 5.
- MCMC works well in high-dimensional problems, especially for multi-modal likelihoods/posteriors.
- INLA is an R package to fit generalized linear mixed models (including models with spatiotemporal information) using *integrated nested Laplace approximations*...very powerful and very fast. Uses Newton-Raphson to obtain posterior mode.
- BayesX is another free package to fit generalized linear mixed models, as well as semiparametric survival models, competing risks, etc. Allows for additive predictors, varying coefficient models and spatially-varying random effects. R2BayesX package allows fitting in R. Both approximate (fast) inference and more exact (MCMC, slower) inference is possible.
- Next topic: Monte Carlo integration.