

STAT 714 HW 5 SOLUTIONS

[1] For matrices X , A , and B

(a) show that $A X^T X = B X^T X \iff A X^T = B X^T$.

(b) show that $X(X^T X)^-$ is a gen. inverse of X^T .

Solution:

(a) " $\Leftarrow$ " Suppose $A X^T = B X^T$. Then post-multiplication by X gives $A X^T X = B X^T X$.

" $\Rightarrow$ " Suppose $A X^T X = B X^T X$. This implies

$$X^T X A^T = X^T X B^T \Rightarrow X^T X (A^T - B^T) = 0,$$

so the columns of $A^T - B^T$ are in $\text{Nul } X^T X$.

Since $\text{Nul } X^T X = \text{Nul } X$ (we have shown this in class), we have

$$X(A^T - B^T) = 0 \Rightarrow X A^T = X B^T \Rightarrow A X^T = B X^T.$$

(b) Write $X^T X (X^T X)^- X^T X = X^T X$.

This implies $X^T X \underbrace{(X^T X)^-}_{X^T} X^T = X^T$ by the result proven in (a).

Therefore $X(X^T X)^-$ is a generalized inverse of X^T .

[2] let $Y_i = \mu + \sum_{j=1}^d g_{ij} \beta_j + \epsilon_i$ for $i=1, \dots, n$,

let $(g_{ij})_{1 \leq i \leq n, 1 \leq j \leq d}$ have full-column rank and suppose $\sum_{j=1}^d g_{ij} = 1 \quad \forall i=1, \dots, n$.

(a) Give representation $\underline{y} = X \underline{b} + \underline{e}$

(b) Check if μ is estimable

(c) Give matrix C such that $C \underline{b} = \underline{0}$ imposes $\sum_{j=1}^d \sum_{i=1}^n g_{ij} \beta_j = 0$.

(d) Find $\hat{\mu}$ under the constraint in (c).

Solution:

$$(a) \quad \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & g_{11} & \dots & g_{1d} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & g_{n1} & \dots & g_{nd} \end{bmatrix} \begin{bmatrix} \mu \\ \beta_1 \\ \vdots \\ \beta_d \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}.$$

$$\underline{y} = X \underline{b} + \underline{e}$$

(b) $\mu = \underline{c}^T \underline{b}$ with $\underline{c} = (1 \ 0 \dots 0)^T$.

To check whether $\underline{c} \in \text{Col } X^T$, build augmented matrix for solving $X^T \underline{x} = \underline{c}$ and row reduce:

$$\left[\begin{array}{ccc|c} 1 & \dots & 1 & 1 \\ g_{11} & \dots & g_{n1} & 0 \\ \vdots & & \vdots & \vdots \\ g_{1d} & \dots & g_{nd} & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 0 & \dots & 0 & 1 \\ g_{11} & \dots & g_{n1} & 0 \\ \vdots & & \vdots & \vdots \\ g_{1d} & \dots & g_{nd} & 0 \end{array} \right] \leftarrow \text{subtract from the first row the sum of all the other rows.}$$

We see that there is no solution, so μ is not estimable.

(c) We may impose the constraint $\sum_{j=1}^d \sum_{i=1}^n g_{ij} \beta_j = 0$ as $C \underline{b} = 0$ with

$$C = \left[0 \quad \sum_{i=1}^n g_{i1} \quad \dots \quad \sum_{i=1}^n g_{id} \right]_{1 \times (d+1)}$$

(d) The constrained estimator is the (unique) solution to

$$\begin{bmatrix} X^T X \\ C \end{bmatrix} \underline{b} = \begin{bmatrix} X^T \underline{y} \\ 0 \end{bmatrix}$$

letting $\underline{g}_{ij} = (g_{1j}, \dots, g_{nj})^T$ for each $j=1, \dots, d$, we may write

$$X^T X = \begin{bmatrix} n & \underline{1}_n^T \underline{g}_{\sim 1} & \dots & \underline{1}_n^T \underline{g}_{\sim d} \\ \underline{1}_n^T \underline{g}_{\sim 1} & \left(\underline{g}_{\sim i}^T \underline{g}_{\sim j} \right)_{1 \leq i, j \leq d} & & \\ \vdots & & & \\ \underline{1}_n^T \underline{g}_{\sim d} & & & \end{bmatrix} \quad X^T \underline{y} = \begin{bmatrix} n \bar{y} \\ \underline{g}_{\sim 1}^T \underline{y} \\ \vdots \\ \underline{g}_{\sim d}^T \underline{y} \end{bmatrix}$$

From here we row-reduce the augmented matrix:

$$\left[\begin{array}{cccc|c} n & \underline{1}_n^T \underline{g}_{\sim 1} & \dots & \underline{1}_n^T \underline{g}_{\sim d} & n \bar{y} \\ \underline{1}_n^T \underline{g}_{\sim 1} & \left(\underline{g}_{\sim i}^T \underline{g}_{\sim j} \right)_{1 \leq i, j \leq d} & & & \underline{g}_{\sim 1}^T \underline{y} \\ \vdots & & & & \vdots \\ \underline{1}_n^T \underline{g}_{\sim d} & & & & \underline{g}_{\sim d}^T \underline{y} \\ 0 & \underline{1}_n^T \underline{g}_{\sim 1} & \dots & \underline{1}_n^T \underline{g}_{\sim d} & 0 \end{array} \right]$$

$$\sim \begin{bmatrix} n & 0 & \dots & 0 & | & n\bar{y} \\ \vdots & \vdots & \vdots & \vdots & | & \vdots \\ 1_{n \times d}^T & \begin{pmatrix} g_1^T g_1 \\ \vdots \\ g_d^T g_d \end{pmatrix} & \vdots & \vdots & | & \begin{pmatrix} g_1^T y \\ \vdots \\ g_d^T y \end{pmatrix} \\ 0 & 1_{n \times d}^T g_1 & \dots & 1_{n \times d}^T g_d & | & 0 \end{bmatrix}.$$

Subtract last row from first row

This shows that the first entry of the solution $\hat{b}$ to $\begin{bmatrix} X^T X \\ c \end{bmatrix} b = \begin{bmatrix} X^T y \\ 0 \end{bmatrix}$ is $\bar{y}$.

So $\hat{\mu} = \bar{y}$.

- 13 Let $X_{n \times p}$ have full-column rank with first column a column of ones.
 Let $y_{n \times 1}$ a vector of responses not all equal to the same value.
 Let P_2 be the orth. proj. onto $\text{Span}\{1_n\}$.

(a) Interpret $\frac{\|(P_X - P_2)y\|^2}{\|(I - P_2)y\|^2}$.

(b) Give range of values for quantity in (a)

(c) Write quantity in terms of $y_i, \hat{y}_i, \bar{y}$.

Solution:

(a) This is the ratio of the "model sum of squares" over the "total sum of squares".

The denominator measures the total variability in y around its mean.

The numerator measures the variability of $P_X y$ around the mean of y .

This is R^2 , the coefficient of determination.

(b) we can write

$$\begin{aligned}\|(\mathbf{I} - \mathbf{P}_1)\tilde{\mathbf{y}}\|^2 &= \|(\mathbf{I} - \mathbf{P}_x)\tilde{\mathbf{y}} + (\mathbf{P}_x - \mathbf{P}_1)\tilde{\mathbf{y}}\|^2 \\ &= \|(\mathbf{I} - \mathbf{P}_x)\tilde{\mathbf{y}}\|^2 + \|(\mathbf{P}_x - \mathbf{P}_1)\tilde{\mathbf{y}}\|^2 + 2 [(\mathbf{P}_x - \mathbf{P}_1)\tilde{\mathbf{y}}] \cdot [(\mathbf{I} - \mathbf{P}_x)\tilde{\mathbf{y}}],\end{aligned}$$

where

$$\begin{aligned}[(\mathbf{P}_x - \mathbf{P}_1)\tilde{\mathbf{y}}] \cdot [(\mathbf{I} - \mathbf{P}_x)\tilde{\mathbf{y}}] &= \tilde{\mathbf{y}}^T (\mathbf{P}_x - \mathbf{P}_1) (\mathbf{I} - \mathbf{P}_x) \tilde{\mathbf{y}} \\ &= - \tilde{\mathbf{y}}^T \mathbf{P}_1 (\mathbf{I} - \mathbf{P}_x) \tilde{\mathbf{y}} \\ &= - \tilde{\mathbf{y}}^T (\mathbf{P}_1 - \mathbf{P}_1 \mathbf{P}_x) \tilde{\mathbf{y}}, \\ &= 0,\end{aligned}$$

since $\mathbf{P}_1 \mathbf{P}_x = \mathbf{P}_1$.

To see why $\mathbf{P}_1 \mathbf{P}_x = \mathbf{P}_1$, note that

$$\mathbf{P}_x \mathbf{P}_1 \tilde{\mathbf{y}} = \mathbf{P}_1 \tilde{\mathbf{y}} \quad \forall \tilde{\mathbf{y}} \text{ since } \mathcal{R}_{\mathbf{P}_1} \{\tilde{\mathbf{y}}\} \subset \mathcal{C}(\mathbf{X}).$$

since $\mathbf{X}$ has a column of ones
↓

This gives $\mathbf{P}_x \mathbf{P}_1 = \mathbf{P}_1 \Rightarrow (\mathbf{P}_x \mathbf{P}_1)^T = \mathbf{P}_1^T = \mathbf{P}_1 \Rightarrow \mathbf{P}_1 \mathbf{P}_x = \mathbf{P}_1$.

From the above we have

$$\|(\mathbf{I} - \mathbf{P}_1)\tilde{\mathbf{y}}\|^2 = \|(\mathbf{I} - \mathbf{P}_x)\tilde{\mathbf{y}}\|^2 + \|(\mathbf{P}_x - \mathbf{P}_1)\tilde{\mathbf{y}}\|^2.$$

so the numerator $\|(\mathbf{P}_x - \mathbf{P}_1)\tilde{\mathbf{y}}\|^2$ can never exceed the denominator $\|(\mathbf{I} - \mathbf{P}_1)\tilde{\mathbf{y}}\|^2$.

The denominator is positive and the numerator is nonnegative, so

$$\frac{\|(\mathbf{P}_x - \mathbf{P}_1)\tilde{\mathbf{y}}\|^2}{\|(\mathbf{I} - \mathbf{P}_1)\tilde{\mathbf{y}}\|^2} \in [0, 1].$$

4] Let $X = [\tilde{x}_1 \ X_2]$, where X_2 has a column of ones and X has full-column rank.

Let $\hat{b}_1 = (X^T X)^{-1} X^T y$.

(a) Show that $\text{Var } \hat{b}_1 = \frac{\sigma^2}{1 - R_1^2} \frac{1}{\|(\mathbf{I} - P_1)\tilde{x}_1\|^2}$, where $R_1^2 = \frac{\|(P_{X_2} - P_1)\tilde{x}_1\|^2}{\|(\mathbf{I} - P_1)\tilde{x}_1\|^2}$.

(b) Interpret.

Solution:

(a) We have
$$\begin{aligned} \text{Cov } \hat{b}_1 &= \text{Cov} \left((X^T X)^{-1} X^T y \right) \\ &= (X^T X)^{-1} X^T [\sigma^2 \mathbf{I}_n] X (X^T X)^{-1} \\ &= \sigma^2 (X^T X)^{-1}. \end{aligned}$$

The variance of $\hat{b}_1$ is the (1,1) entry of $\sigma^2 (X^T X)^{-1}$.

Using a block matrix inversion formula, we obtain

$$\begin{aligned} \text{Var } \hat{b}_1 &= \sigma^2 \left[\tilde{x}_1^T \tilde{x}_1 - \tilde{x}_1^T X_2 (X_2^T X_2)^{-1} X_2^T \tilde{x}_1 \right]^{-1} \\ &= \frac{\sigma^2}{\tilde{x}_1^T (\mathbf{I} - P_{X_2}) \tilde{x}_1} \\ &= \frac{\sigma^2}{\tilde{x}_1^T ((\mathbf{I} - P_1) - (P_{X_2} - P_1)) \tilde{x}_1} \\ &= \frac{\sigma^2}{\underbrace{\tilde{x}_1^T (\mathbf{I} - P_1) \tilde{x}_1}_{\tilde{x}_1^T (\mathbf{I} - P_1) \tilde{x}_1} - \underbrace{\tilde{x}_1^T (P_{X_2} - P_1) \tilde{x}_1}_{\tilde{x}_1^T (P_{X_2} - P_1) \tilde{x}_1}} \\ &= \frac{\sigma^2}{1 - R_1^2} \frac{1}{\|(\mathbf{I} - P_1)\tilde{x}_1\|^2}. \end{aligned} \quad \left[\begin{array}{l} \text{Note: } \tilde{x}_1^T (P_{X_2} - P_1) \tilde{x}_1 = \|(P_{X_2} - P_1)\tilde{x}_1\|^2 \\ \text{uses the fact that } P_{X_2} - P_1 \text{ is idempotent.} \\ \text{This is idempotent because } \text{Span}(\tilde{x}_2) \subset \text{Col}(X_2) \end{array} \right]$$

(b) As R_1^2 approaches 1, $\text{Var } \hat{b}_1$ will "explode". The quantity R_1 expresses how correlated $\tilde{x}_1$ is with the other columns of X . High correlation/collinearity leads to high variance.

5 Let $\underline{y} = \underline{X}\underline{b} + \underline{e}$, where $\mathbb{E} \underline{e} = \underline{0}$ and $\text{Cov } \underline{e} = \sigma^2 \underline{I}_n$.

Assume eigenvalues of $\underline{X}^T \underline{X}$ are all positive.

(a) Show that $\underline{X}^T \underline{X} \underline{b} = \underline{X}^T \underline{y}$ has a unique solution.

(b) Show $\mathbb{E} \|\hat{\underline{b}} - \underline{b}\|^2 = \sigma^2 \sum_{j=1}^p \lambda_j^{-1}$, where $\lambda_1, \dots, \lambda_p$ are the eigenvalues of $\underline{X}^T \underline{X}$.

Solution:

(a) Since $\underline{X}^T \underline{X}$ has all positive eigenvalues its determinant is nonzero and therefore it is invertible. So

$$\hat{\underline{b}} = (\underline{X}^T \underline{X})^{-1} \underline{X}^T \underline{y}.$$

(b) We have

$$\begin{aligned} \mathbb{E} \|\hat{\underline{b}} - \underline{b}\|^2 &= \mathbb{E} \left(\hat{\underline{b}}^T \hat{\underline{b}} - 2 \hat{\underline{b}}^T \underline{b} + \underline{b}^T \underline{b} \right) \\ &= \mathbb{E} \hat{\underline{b}}^T \hat{\underline{b}} - \underline{b}^T \underline{b} \quad \downarrow \quad \mathbb{E} \underline{z}^T A \underline{z} = (\mathbb{E} \underline{z})^T A \mathbb{E} \underline{z} + \text{tr}(A(\text{Cov } \underline{z})). \\ &= \underline{b}^T \underline{b} + \text{tr}(\text{Cov } \hat{\underline{b}}) - \underline{b}^T \underline{b} \\ &= \text{tr}(\text{Cov } \hat{\underline{b}}) \\ &\quad \downarrow \quad \text{Cov } \hat{\underline{b}} = \sigma^2 (\underline{X}^T \underline{X})^{-1}. \\ &= \sigma^2 \text{tr}((\underline{X}^T \underline{X})^{-1}) \\ &= \sigma^2 \sum_{j=1}^p \frac{1}{\lambda_j}. \end{aligned}$$

Since λ_j^{-1} , $j=1, \dots, p$ are the eigenvalues of $(\underline{X}^T \underline{X})^{-1}$ and the trace of a matrix is the sum of its eigenvalues.

16 Show under $y = X\beta + e$, $E e = 0$, a contrast $c^T \beta$ is estimable $\Leftrightarrow c \in \text{Col } X^T$.

Solution: Firstly, note that $\text{Cov } e$ plays no role in determining estimability of a contrast (in fact we established this result under $E e = 0$, so one could have any kind of covariance structure for e).

"Estimable" means there exists a_0 and a such that $E[a_0 + a^T y] = c^T \beta \quad \forall \beta$.

" $\Leftarrow$ " Let $c \in \text{Col } X^T$. Then $\exists a$ such that $c = X^T a$.

Then with $a_0 = 0$ we have $E[a_0 + a^T y] = a^T X \beta = c^T \beta \quad \forall \beta$.

" $\Rightarrow$ " Suppose $E[a_0 + a^T y] = c^T \beta$ for all β .

Then $a_0 + a^T X \beta = c^T \beta \quad \forall \beta$,

which implies $a_0 = 0$ and $a^T X = c^T$, so $c \in \text{Col } X^T$.

7 Let $X = [\underline{x}_1 \dots \underline{x}_p]$ be full-rank with unit columns.

Find the unit vector $\underline{z}$ and the scalar A such that $\underline{z}^T \underline{x}_j = A$ for $j=1, \dots, p$.

Solution:

The condition $\underline{z}^T \underline{x}_j = A$ for $j=1, \dots, p$ may be expressed as $X^T \underline{z} = A \underline{1}_p$.

A solution is given by

$$\underline{z}^* = (X^T)^- A \underline{1}_p,$$

where $(X^T)^-$ is a generalized inverse of X^T .

A generalized inverse of X^T is $X(X^T X)^{-1}$, since $X^T X (X^T X)^{-1} X^T = X^T$.

So we can write $\underline{z}^* = A X (X^T X)^{-1} \underline{1}_p$.

But we must scale the solution so that it has unit norm. This gives

$$\underline{z} = \frac{1}{\|\underline{z}^*\|} \underline{z}^* = \frac{1}{\sqrt{A^2 \underline{1}_p^T (X^T X)^{-1} X^T X (X^T X)^{-1} \underline{1}_p}} A X (X^T X)^{-1} \underline{1}_p = \frac{1}{\|X (X^T X)^{-1} \underline{1}_p\|} X (X^T X)^{-1} \underline{1}_p.$$

Then

$$X^T \underline{z} = X^T X (X^T X)^{-1} \underline{1}_p \frac{1}{\|X (X^T X)^{-1} \underline{1}_p\|} = \frac{1}{\|X (X^T X)^{-1} \underline{1}_p\|} \underline{1}_p,$$

so $A = \frac{1}{\|X (X^T X)^{-1} \underline{1}_p\|}$. We can also write

$$A = [\underline{1}_p^T (X^T X)^{-1} \underline{1}_p]^{-\frac{1}{2}}$$

$$\underline{z} = [\underline{1}_p^T (X^T X)^{-1} \underline{1}_p]^{-\frac{1}{2}} X (X^T X)^{-1} \underline{1}_p.$$