

## STAT 824 hw 03

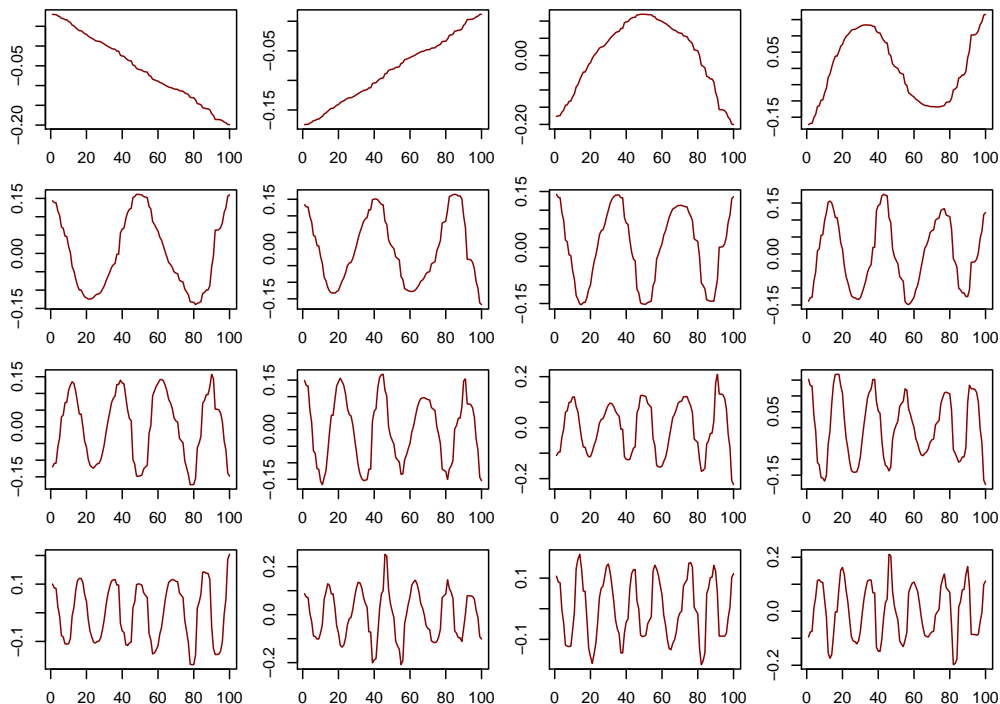
Cox-deBoor recursion, largest eigenvalue of a matrix, smoothing and penalized splines, Lindeberg CLT, least-squares splines

1. Use the Cox-deBoor recursion formula to find the quadratic B-spline function  $N_{0,2}$  based on the knots  $0, 1/3, 2/3, 1$ .
2. Let  $\mathbf{A}$  be a  $d \times d$  matrix such that  $\mathbf{A} = \sum_{j=1}^d \lambda_j u_j u_j^T$ , where  $u_j^T u_k = 1$  if  $j = k$  and  $u_j^T u_k = 0$  if  $j \neq k$  and  $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_d > 0$ . Note that any  $\mathbf{x} \in \mathbb{R}^d$  can be represented as  $\mathbf{x} = \sum_{j=1}^d c_j u_j$ , since the eigenvectors of  $\mathbf{A}$  form a basis for  $\mathbb{R}^d$ .
  - (a) Show that for any  $\mathbf{x} \in \mathbb{R}^d$ , we have  $\frac{\mathbf{x}^T \mathbf{A} \mathbf{x}}{\|\mathbf{x}\|_2^2} \leq \lambda_1$ .
  - (b) Show that for  $\mathbf{x} = a \cdot u_1$ ,  $a \in \mathbb{R}$ , we have  $\frac{\mathbf{x}^T \mathbf{A} \mathbf{x}}{\|\mathbf{x}\|_2^2} = \lambda_1$ .
3. For the smoothing spline estimator

$$\hat{m}_n^{\text{sspl}} = \underset{g \in \mathcal{W}_2}{\text{argmin}} \sum_{i=1}^n [Y_i - g(X_i)]^2 + \lambda \int_0^1 [g''(x)]^2 dx$$

Green and Yandell (1985), [1], give details for computing the smoother matrix  $\mathbf{S}$ , which is the matrix such that  $(\hat{m}_n^{\text{sspl}}(X_1), \dots, \hat{m}_n^{\text{sspl}}(X_n))^T = \mathbf{S} \mathbf{Y}$ . Specifically,  $\mathbf{S} = (\mathbf{I}_n + \lambda \mathbf{K})^{-1}$ , with  $\mathbf{K} = \mathbf{\Delta}^T \mathbf{C}^{-1} \mathbf{\Delta}$ , where, for  $h_i = X_{i+1} - X_i$  (assume that  $X_1, \dots, X_n$  are sorted in increasing order),  $\mathbf{\Delta}$  is a tridiagonal  $(n-2) \times n$  matrix with  $\Delta_{ii} = 1/h_i$ ,  $\Delta_{i,i+1} = -(1/h_i + 1/h_{i+1})$ ,  $\Delta_{i,i+2} = 1/h_{i+1}$ , and  $\mathbf{C}$  is a symmetric  $(n-2) \times (n-2)$  tridiagonal matrix with  $C_{i-1,i} = C_{i,i-1} = h_i/6$  and  $C_{ii} = (h_i + h_{i+1})/3$ .

- (a) Generate  $X_1, \dots, X_n \stackrel{\text{ind}}{\sim} \text{Uniform}(-2, 2)$  for  $n = 100$ , compute the matrix  $\mathbf{S}$ , and then plot the first 16 eigenvectors. The plot should look something like this:



- (b) Now generate  $Y_i = m(X_i) + \varepsilon_i$ ,  $i = 1, \dots, n$ , where  $m$  is a function of your choosing. Then make a scatter plot of your  $(X_1, Y_1), \dots, (X_n, Y_n)$  values with the true function overlaid. Then plot the values  $\hat{m}_n^{\text{sspl}}(X_1), \dots, \hat{m}_n^{\text{sspl}}(X_n)$  against  $X_1, \dots, X_n$ , for some value of  $\lambda$  that makes the estimator look close to the true function.
- (c) On the same data, fit a penalized spline estimator with the same  $\lambda$  value and some fairly large number of knots (you can choose). Compare the fit of the smoothing splines and the penalized splines estimator.
4. For each  $n \geq 1$ , let  $Y_i = x_i\beta + \varepsilon_i$ ,  $i = 1, \dots, n$ , where  $\varepsilon_1, \dots, \varepsilon_n$  are iid with  $\mathbb{E}\varepsilon_1 = 0$  and  $\text{Var } \varepsilon_1 = \sigma^2 < \infty$  and  $x_1, \dots, x_n$  are deterministic, and let  $\hat{\beta}_n = \sum_{i=1}^n x_i Y_i / \sum_{i=1}^n x_i^2$ . Use the corollary to the Lindeberg Central Limit Theorem given in Lec 04 to show that

$$\frac{\max_{1 \leq i \leq n} |x_i|}{\sqrt{\sum_{i=1}^n x_i^2}} \rightarrow 0 \text{ as } n \rightarrow \infty$$

implies  $\sqrt{n}(n^{-1} \sum_{i=1}^n x_i^2)^{1/2}(\hat{\beta}_n - \beta)/\sigma \rightarrow N(0, 1)$  in distribution as  $n \rightarrow \infty$ .

5. For a sample size of  $n = 200$ , generate  $Y_i = m(X_i) + \varepsilon_i$ , for  $i = 1, \dots, n$ , where  $\varepsilon_1, \dots, \varepsilon_n \stackrel{\text{ind}}{\sim} \text{Normal}(0, 1)$ ,  $X_1, \dots, X_n \stackrel{\text{ind}}{\sim} \text{Uniform}(-2, 2)$ , and with  $m(x) = -50(x - 1/2)\phi(2(x - 1/2))$ .
- (a) Construct an estimate of  $m$  with a least squares splines estimator using cubic B splines basis functions; choose some number  $K_n$  of intervals into which to subdivide the range of the covariate values, and position the knots at equally spaced quantiles of  $X_1, \dots, X_n$ . Plot your estimator of  $m$  as well as the true function on a scatterplot of the  $(X, Y)$  values.
- (b) The number of intervals  $K_n$  into which we break the range of the covariate values plays an important role in least-squares splines estimation. Run a simulation: On each of 500 simulated data sets, build a 95% confidence interval for  $m(x_0)$  at the point  $x_0 = 0$  based on your least-squares splines estimator under  $K_n = 1, \dots, 15$ . So for each data set you will have 15 confidence intervals. Record for each choice of  $K_n$  the proportion of times the confidence interval contained the true value of  $m(x_0)$  as well as the average width of the confidence intervals across the 500 data sets. Arrange your results in a table like the one below (this is the table I got, so your numbers should be fairly close to these):

$K_n$	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
coverage	0.00	0.00	0.00	0.24	0.05	0.72	0.65	0.87	0.93	0.94	0.96	0.95	0.95	0.95	0.94
average width	0.40	0.53	0.50	0.62	0.59	0.71	0.69	0.79	0.80	0.87	0.90	0.95	0.98	1.03	1.06

- (c) Why does the average width keep getting wider as  $K_n$  increases?
- (d) Why does the coverage start out too low and then stabilize around 0.95 as  $K_n$  increases?

## References

- [1] Peter J Green and Brian S Yandell. Semi-parametric generalized linear models. In *Generalized linear models*, pages 44–55. Springer, 1985.