

Issues with Bayes Factors

- ▶ **Note:** When an **improper prior** is used for θ , the Bayes Factor is not well-defined.
- ▶ Note $B(\mathbf{x}) = \frac{\text{Posterior odds for } M_1}{\text{Prior odds for } M_1}$, and the “prior odds” is meaningless for an improper prior.
- ▶ Gill’s Sec. 7.3.2 suggests several methods (Local Bayes factors, Intrinsic Bayes Factors, Partial Bayes Factors, Fractional Bayes Factors), none of them ideal, to define types of Bayes Factors with improper priors.
- ▶ One criticism of Bayes Factors is the (implicit) assumption that one of the competing models (M_1 or M_2) is correct.
- ▶ Another criticism is that the Bayes Factor depends heavily on the choice of prior.

The Bayesian Information Criterion

- ▶ The Bayesian Information Criterion (*BIC*) can be used (as a substitute for the Bayes factor) to compare two (or more) models.
- ▶ Conveniently, the *BIC* does **not** require specifying priors.
- ▶ For parameters θ and data \mathbf{x} :

$$BIC = -2 \ln L(\hat{\theta}|\mathbf{x}) + p \ln(n)$$

where p is the number of free parameters in the model, and $L(\hat{\theta}|\mathbf{x})$ is the **maximized likelihood**, given observed data \mathbf{x} .

- ▶ Good models have relatively small *BIC* values:
 - ▶ A small value of $-2 \ln L(\hat{\theta}|\mathbf{x})$ indicates good fit to the data;
 - ▶ a small value of the “overfitting penalty” term $p \ln(n)$ indicates a simple, parsimonious model.

The Bayesian Information Criterion

- ▶ To compare two models M_1 and M_2 , we could calculate

$$\begin{aligned} S &= -\frac{1}{2}[BIC_{M_1} - BIC_{M_2}] \\ &= \ln L(\hat{\theta}_1|\mathbf{x}) - \ln L(\hat{\theta}_2|\mathbf{x}) - \frac{1}{2}(p_1 - p_2) \ln(n) \end{aligned}$$

- ▶ A small value of S would favor M_2 here and a large S would favor M_1 .
- ▶ As $n \rightarrow \infty$,

$$\frac{S - \ln(B(\mathbf{x}))}{\ln(B(\mathbf{x}))} \rightarrow 0$$

and for large n ,

$$BIC_{M_1} - BIC_{M_2} = -2S \approx -2 \ln(B(\mathbf{x})).$$

The Bayesian Information Criterion

- ▶ Note that differences in BIC 's can be used to compare several nonnested models.
- ▶ They should be trusted as a substitute for Bayes Factors only when (1) no reliable prior information is available and (2) when the sample size is **quite large**.
- ▶ See R examples: (1) Calcium data example and (2) Regression example on Oxygen Uptake data set.

CHAPTER 10 SLIDES BEGIN HERE

Hierarchical Models

- ▶ In **hierarchical Bayesian estimation**, we not only specify a prior on the data model's parameter(s), but specify a further prior (called a **hyperprior**) for the hyperparameters.
- ▶ This more complicated prior structure can be useful for modeling **hierarchical data structures**, also called *multilevel data*.
- ▶ Multilevel data involves a hierarchy of nested populations, in which data could be measured for several levels of aggregation.

Examples:

- ▶ We could measure white-blood-cell counts for numerous patients within several hospitals.
- ▶ We could measure test scores for numerous students within several schools.

Hierarchical Bayes Estimation

- ▶ Assume we have data \mathbf{x} from density $f(\mathbf{x}|\theta)$ with a parameter of interest θ .
- ▶ Typically we would choose a prior for θ that depends on some hyperparameter(s) ψ .
- ▶ Instead of choosing fixed values for ψ , we could place a **hyperprior** $p(\psi)$ on it.
- ▶ Note that this hierarchy could continue for any number of levels, but it is rare to need more than two levels for the prior structure.

Hierarchical Bayes Estimation

- ▶ Our posterior is then:

$$\pi(\theta, \psi | \mathbf{x}) \propto L(\theta | \mathbf{x}) p(\theta | \psi) p(\psi)$$

- ▶ Posterior inference about θ is based on the **marginal** posterior for θ :

$$\pi(\theta | \mathbf{x}) = \int_{\psi} \pi(\theta, \psi | \mathbf{x}) d\psi$$

- ▶ Except in simple situations, such analysis typically requires MCMC methods.